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User manual

## Z10TL

10x Zoom IR Laser Night Vision Object Tracking Gimbal Camera Compatible with DJI M200/M210/M210RTK and V2


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## Z10TL High-precision Camera

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## Camera Introduction

Z10TL is a high-precision professional 3-axis gimbal camera which features high stability, small size, light weight and low power consumption. The 3-axis gimbal based on FOC motor control technology, adopts high-precision encoder in each motor. It' s developed based on DJI PSDK, comptible with DJI drones M200 / M210 / M210RTK and V2 series. Controlled by APP "DJI Pilot" it can fulfill many powerful functions, such as: shoots or records with 10 times optical zoom, object tracking, IR laser night vision and so on. The speed of Z10TL gimbal is adjustable, LOW speed mode for tele end, the control will be more accurate. Fast mode for wide end, which makes the gimbal control sensitive and quick. Also the one-key to center function will allow the gimbal return to initial position automatically and rapidly. You can input a degree in APP Payload Setting and get the gimbal attitude angles exactly.

## Camera Description



Please make sure that the motor is not stopped by any object during the rotation, if the gimbal is blocked during rotation, please remove the obstruction immediately.

## Mechanics@Electronic Characteristics

| Input voltage | $3 \mathrm{~S} \sim 4 \mathrm{~S}$ | Idle current | $330 \mathrm{mA@12V}$ |
| :--- | :--- | :--- | :--- |
| Dynamic current | $450 \mathrm{~mA} @ 12 \mathrm{~V}$ | Working <br> environment temp | $-40 \mathrm{C} \sim+60 \mathrm{C}$ |
| Size | $129.8^{\star} 117.1^{*} 119.8 \mathrm{~mm}$ | Weight | 554 g |

Pitch/Tilt: Pitch angle range of action : $\pm 90$
Roll: Roll angle range of action : $\pm 85^{\circ}$
Yaw/Pan: Yaw angle range of action : $\pm 360^{\circ}$
Vibration angle: Pitch/Roll: $\pm 0.02^{\circ}$, Yaw: $\pm 0.03^{\circ}$

## Application Description

## DJI Pilot

After mounting Z10TL on DJI drone and connecting with remote control, you can operate the gimbal camera via APP DJI Pilot. The gimbal attitude angels (tilt and pan) can be controlled by DJI remote control. Control method please refer to DJI related user manual.

## 1. Menu instruction



### 1.1 Camera settings - Photo mode settings:

You can format SD card on Pilot, choose single shot, burst mode or interval mode.

1.2 Payload Settings:


## Gimbal Speed:

Gimbal speed is adjustable. When it's $0 \%$, the speed will be adjust automatically, quick speed for wide end, slow speed for tele end. When you adjust it to $1 \%$ manually, the speed will be low even in wide end. The high the percentage is, the quicker the speed will be.


## OSD Display Options:

You can DIY you on-screen-display (OSD). Choose Hide All, then you can choose to display the items you want only.


Hide All:


## OSD Type Options:

You can choose to display FOV (Field of View) or Zoom times on the OSD, GPS coordinate of UAV or the object (estimate).


## Digital Zoom Options:

The EO camera of Z10TL has 6 times digital zoom. Press T continually will get digital zoom automatically after 10x full optical zoom.
The zoom times number will become blue when it's in digital zoom status. You can also disable digital zoom in camera settings.


## Camera Settings:

Choose defog, flip the screen or Dzoom (digital zoom) on/off when necessary.


## Gimbal Pitch / Yaw Angle Settings:

Input the pitch / yaw angle degrees to get exact attitude angles directly.


## 2. Main functions instruction

### 2.1 IR laser light for Night Mode

Z10TL can let you see clearly even in a pitch-dark environment with an invisible light. Switch on IR light (then Night Mode will be turned on automatically), you will see a laser light beam on the target directly. The light beam size is adjustable. It will be divergent for wide end and condensed for tele end automatically. You can also adjust the light beam size manually from Payload Settings, then zoom to see clearly.



### 2.2 Object tracking

Start tracking: Enable tracking function, then single touch on the screen to pick tracking object.
Stop tracking: Payload Settings --CANCEL TRACKING
*Note: the gimbal will follow the object automatically after object is chosen, to control the gimbal manually please cancel tracking first.


## Specification

|  | Hardware Parameter |
| :---: | :---: |
| Working voltage | 12 V |
| Input voltage | 3S ~ 4S |
| Dynamic current | 1100mA@12V |
| Idle current | 800mA @ 12V |
| Power consumption | $\leq 13.2 \mathrm{~W}$ |
| Working environment temp. | $-40^{\circ} \mathrm{C} \sim+60^{\circ} \mathrm{C}$ |
| Output | Skyport |
| Local-storage | SD card (Up to 128G, class 10, FAT32 or ex FAT format) |
| Control method | DJI Pilot |
|  | Gimbal Spec |
| Pitch/Tilt | $\pm 90^{\circ}$ |
| Roll | $\pm 85^{\circ}$ |
| Yaw/Pan | $\pm 360^{\circ *} \mathrm{~N}$ |
| Vibration angle | Picth/Roll: $\pm 0.02^{\circ}$, Yaw: $\pm 0.03^{\circ}$ |
| One-key to center | $\checkmark$ |
|  | Camera Spec |
| Imager Sensor | 1/2.8" CMOS |
| Picture quality | Full HD 1080 (1920*1080) |
| Effective pixel | 2.43 MP |
| Lens optical zoom | $10 \mathrm{x}, \mathrm{F}=4.7 \sim 47 \mathrm{~mm}$ |
| Digital zoom | 6 x |
| Min object distance | 1.5 m |
|  | Horizontal: $58.7^{\circ}$ (wide end) $\sim 3.2^{\circ}$ (tele end) |
| View angle | Vertical: $45^{\circ}$ (wide end) $\sim 2.4^{\circ}$ (tele end) |
|  | Focus: $70.9^{\circ}$ (wide end) $\sim 7.1^{\circ}$ (tele end) |
| Sync system | Progressive scanning |
| S/N ratio | $\geq 52 \mathrm{~dB}$ |
| Min illumination | Color 0.05lux@F1.6 |
| Focus | Auto |
| Gain | Auto |
| White balance | Auto / Manual |
| Shutter speed | Auto |
| Image rotation | $180^{\circ}$, Horizontal/Vertical mirror image |
| User presetting bit | 20 sets |
| Defog | Yes |
| OSD | Yes |

Camera Object Tracking

| Update rate of deviation pixel | 50 Hz |
| :--- | :--- |
| Output delay of deviation pixel | $<10 \mathrm{~ms}$ |
| Minimum object contrast | $5 \%$ |
| SNR | 4 |
| Minimum object size | $16^{\star} 16$ pixel |
| Maximum object size | $160^{\star} 160$ pixel |
| Tracking speed | $\pm 32$ pixel/frame |
| Object memory time | 100 frames (4s) |
| The mean square root values of pulse | $<0.5$ pixel |
| noise in the object position | 300 meters |
| Effective range | power zoom synchronously, $70^{\circ} \sim 2.0^{\circ}$ adjustable |
| Illumination angle | 554 g |
| N.W. | $129.8^{\star 1117.1^{*} 119.8 m m}$ |
| Product meas. | 1 pc gimbal camra device / box |
| Accessories |  |

